

Atmospheric Water Extraction Enabled by Smart Moisture Absorbing Foams (SMAFs)

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VG-2021-197-1

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Team Members and Roles

VG-2021-197-2

- Physical Sciences Inc., PSI (Program Lead)
 - Program Role: Sorbent development, evaluation and optimization (TA1). AWE system modelling, design, prototyping and evaluation (TA2). Management and reporting.
 - **Expertise:** Tech development for large government programs.
- University of Massachusetts Amherst, UMass (TA1 Partner)
 - Program Role: Sorbent material synthesis, characterization and scale-up.
 - **Expertise:** World class Polymer Science and Engineering program.
- Cascade Designs, CDI (TA2 Partner)
 - Program Role: Prototype system development, optimization and field testing.
 Commercialization partner, owner of Mountain Scientific Research (MSR) brand.
 - **Expertise:** Design and manufacture of individual sustainment gear.



PSI Smart Sorbent Platform





MSR/CDI Water Filtration Systems

Program Summary



Team:

- VG-2021-197-3
- Physical Sciences Inc. (PSI), Andover, MA (PI: Gamliel, PM: Warren)
- University of Massachusetts Amherst, Amherst, MA (Co-I: Emrick)
- Cascade Designs Inc (CDI), Seattle, WA (Co-I: Norris)
- Primary Objective Develop a man portable system capable of extracting potable drinking water from air, obviating the need for costly and dangerous transportation (Expeditionary Track).
 - TA1 Goal: Create a new and revolutionary class of sorbents that have high capacity, rapid water uptake and release sorbed water by compressionenabled switching from hydrophilic to hydrophobic state.
 - TA2 Goal: Design, construct and optimize a system capable of meeting the DARPA SWaP and output requirements by leveraging the SMAF compressive release capability developed in TA1.



VG-2021-197-4

- **Topic** DARPA BAA HR001120S0014 Atmospheric Water Extraction (AWE)
- **Broad Need** Water transport to the warfighter is mission-critical but logistically challenging, requiring equipment, fuel, and personnel that limits tactical maneuver and decision space. Warfighter requires 3-7 L/day of drinking water.

Metrics	Phase I Objective	Phase II Objective
Water Production Rate	≥1 L/day @ ~4 °C, 50% RH ≥1 L/day @ ~27 °C, 10% RH ≥1 L/day @ ~43 °C, 60% RH	≥5.5 L/day @ ~4 °C, 50% RH ≥5.5 L/day @ ~27 °C, 10% RH ≥7.5 L/day @ ~43 °C, 60% RH
System Dry Weight	≤7 kg	≤2.5 kg
Power	Must be contained onboard	Must be contained onboard
Volume	6 L (0.21 ft ³)	1.5 L (0.05 ft ³)
Desired Properties	-	Water meets TB-Med-577 potability standards, Operational for >30 days at 24 hr runtime

• "The world's ultimate weapon runs on water; everything else runs on fuel"



Key Innovation – Compressive Release

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TA1 Smart Moisture Absorbing Foam (SMAF) designed to have **water capture**, **storage** and **release** functionality (non-thermal release mechanism)

TA1: Material Level Concept



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Exp. Results	Milestone 1.1 Metric	Matrix 1	Matrix 2
Water Uptake at 100% RH (g_{H2O}/g_{foam})	> 10	12.5	11

Functional groups selected based on experimental evaluation



TA2: System Level Concept

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TA2 design leverages high SMAF capacity and mechanical release to drastically reduce system SWaP



(mg scale)

TA1 - Screening Methods

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(100 mg scale)

Compression Test



Measurement: Force Required for Water Release (q scale)

We have assembled the equipment necessary to measure water capture and release under the relevant conditions

(q scale)



TA1 - Capture Materials Toolbox

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TA1 - Water Storage Development

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Goal: Exceed baseline water uptake of commercial off-the-shelf biopolymer foam **Methods:** Examine biopolymer foaming (by lyophilization) with and without crosslinking





TA1 – Best Performing Materials To Date

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TA1 - M05 SMAF Demonstration

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- Objective: Demonstrate water release from SMAF material loaded at 70% RH
- Methods: Perform water uptake in humidity chamber, followed by release using compression set-up
 - ¹H NMR spectrum indicated contamination of water with polymers



SMAF coupon loaded at 70% RH



Video demonstrates water release upon SMAF compression





TA1 - M08 SMAF Demonstration

VG-2021-197-13

- Objective: Demonstrate water uptake and compressive release at 55% RH (M05 demonstrated at 70 % RH)
 - Fulfills one out of the three DARPA performance conditions (10%, 50%, 60%)





M08 SMAF coupon reached 120% water uptake after 16 hr at 55% RH

Achieved 20% water release with a 45 N force

SMAF water capture and compressive release demonstrated at 55% RH



TA2 – SMAF Model Key Equations

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Governing Equations

Humid Air Flow Through SMAF

- Navier-Stokes (momentum equation)
- Assumptions: constant fluid and SMAF properties, laminar flow, no mass source/sink, gravity negligible
- Brinkman (B) Equations: continuity and momentum conservation for flow through porous media

 $\nabla \cdot \mathbf{U} = 0$



Water Vapor (c_v) and Liquid Water (c_l) Mass Transport

- Assumptions: constant fluid and SMAF properties, liquid water advection negligible
- Advection-Diffusion (AD) equation with reaction rate defines mass transport:

 $\frac{\partial c_i}{\partial t} = D_i \nabla^2 c_i - \mathbf{U}_i \cdot \nabla c_i + R_i$ Transient Diffusion Advection Vapor to Liquid Source/Sink

Key Parameters

Water Capture

- Assumptions: sample size in DVS small enough for diffusion to be negligible, advection also negligible
- LDF model fit to DVS data at various RH:

$$R_l = -R_v = k \big(c_{l,eq} - c_l \big)$$

• k, and $c_{l,eq}$ both function of RH – calculated from local c_v

Key Dimensionless Numbers

- Non-dimesionalization of Advection-Diffusion equations yields three key dimensionless numbers:
- Diffusivity ratio:

$$\lambda = \frac{H_2 0 \text{ in SMAF}}{H_2 0 \text{ in air}} = \frac{D_l}{D_v}$$

Peclet number:

$$Pe_v = \frac{advection}{diffusion} = \frac{u_v L}{D_v}$$

Damkohler number, 2nd kind:
 water canture

$$Da_{v} = \frac{water\ capture\ rate}{diffusion} = \frac{kL^{2}}{D_{v}}$$

Navier-Stokes and Advection/Diffusion Equations used to model water transport and capture by SMAF material

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TA2 – SMAF Model Inputs and Outputs

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The goal of this modeling effort is to correlate intrinsic foam properties (DVS data) to performance in a flow geometry (prototype system)



TA2 – SMAF Model Construction

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MATLAB R2020a	
HOME PLOTS APPS	EDITOR PUBLISH VIEW
HOME PLOTS APPS Image: New Open Save Grind Files Image: Open Save Grind Files Image: New Open Save Image: Open Save Image: Open Save Image: Open Save Image: New Open Save Image: Open Save Image: Open Save Image: Open Save Image: New Open Save Image: Open Save Image: Open Save Image: Open Save Image: New Open Save Image: Open Save Image: Open Save Image: Open Save Image: New Open Save Image: Open Save Image: Open Save Image: Open Save Image: Name Amage: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Name Amage: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save Image: Open Save I	EDITOR PUBLISH VIEW Insert fr fr Comment % % % 7 Indent Free Reactions Breakpoints Breakpoints EDIT Breakpoints Breakpoints Run and Advance Run and Time RUN EDIT BREAKPOINTS BREA
BAD_1D.m 36 BAD_1D.pptx 39 BAD_1D_Graphing.m 40 BAD_1D_NonDim.xlsx 41 BAD_1D_NonDim.Graphing.m 42 BAD_1D_ODE.m 43 BAD_1D_PDEPE.m 43 BAD_1D_PDEPE.m 44 BAD_1D_PDEPE.n 44 BAD_2D_Cylindrical.pptx 45 BAD_2D_Cylindrical.pptx 46	<pre>8 - mdot_ha=mdot_da*(1+x_in); % humid air mass flow rate [g/s] 9 - Vdot_ha=mdot_ha/1000/rho_in; % humid air volumetric flow rate [m^3/s] 0 - u_avg=Vdot_ha/(pi*rm^2); % specific discharge/superficial velocity [m/s] 1 % Reynolds number - check for laminar assumption 2 - Re_open=rho_in*u_avg*2*rm/mu_in; % open tube 3 - Re_foam=rho_in*u_avg*sqrt(kappa/eps_p)/mu_in; % through foam 4</pre>
Cons_covy_round and a second a	<pre>8 9 % Domain discretization 0 - dz=0.0001; % z spatial resolution [m] 1 - z=linspace(0,zm,zm/dz+1); % z domain [m] 2 - dr=0.00005; % r spatial resolution [m]</pre> SMAF model constructed in MATLAB
FIGUARIANSIS Equations.docx 53 Image: State of the	<pre>3 - r=linspace(0,rm,rm/dr+1).'; % r domain [m] 4 - [zG,rG]=meshgrid(z*100,r*100); % gridded [z,r] domain [cm] 5 - t=[0:0.001:1 10:10:100000].';% time domain [s] 6</pre>

TA2 – Predicting SMAF Water Capture Performance

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Animation shows that the PSI model prediction has good correlation with the experimental measurement



TA2 – Tracking Progress Towards Implementation

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- Goal: Provide a predictive modeling to assist in the overall design and ensure the required performance metrics are being met.
 - Black line represents M05 demonstration
 - **Blue line** represents M08 demonstration —
 - Computed using PSI rubber model using several key assumptions



Key Assumptions:

- No SMAF material degradation over time
- Layered system model as initially proposed to estimate housing mass
- Minimal additional pressure drop as SMAF fills. Air flow requirements used to estimate fan and battery mass
- Two capture/release cycles per day
- Water is potable after filtration

Improvements in performance at lower relative humidity and system performance have been achieved



Potential Technology Use Cases

VG-2021-197-19

• **Goal:** Identify potential use cases to which our SMAF approach can be tailored to both defense and commercial applications:

1. Downed Pilot Scenario

Key Advantage: Low anticipated system noise generation

2. Lifeboat Operation

Key Advantage: Surrounding conditions maintained at high RH

3. Initial Household Water Generation after Disaster Event

Key Advantage: Ideal solution for use in tropical regions, where water production can be maximized.



The team is taking into consideration potential applications to guide prototype development

L-6249

Conclusions and Next Steps



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- SMAF material captures water from the atmosphere and releases water by compression
- Core concept has been demonstrated at 55% and 70% relative humidity
- SMAF model developed to described transport and adsorption in foam media
- Next steps include further optimization of SMAF formulation and construction of an operable prototype (due to IV&V team in July)





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Backups

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- **Topic DARPA BAA HR001120S0014** Atmospheric Water Extraction (AWE)
- Broad Need Water transport to the warfighter is mission-critical but logistically challenging, requiring equipment, fuel, and personnel that limits tactical maneuver and decision space. Warfighter requires 3/7 L/day.
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System Dry Weight	≤7 kg	≤2.5 kg
Power	Must be contained onboard	Must be contained onboard
Volume	6 L (0.21 ft ³)	1.5 L (0.05 ft ³)
Unit Cost	-	-
Desired Properties	-	Water meets TB-Med-577 potability standards, Operational for >30 days at 24 hr runtime



PSI Team Program Objectives

VG-2021-197-23

- **Program Goal:** Develop a system capable of extracting potable drinking water from air, obviating the need for costly and dangerous transportation (Expeditionary Track).
 - Program broken into 2 technical areas (TAs)
 - TA1: Transformational Sorbent Materials Development
 - TA2: Extractor Modelling, Engineering and Sorbent Integration
- **TA1 Goal:** Create a new and revolutionary class of sorbents that have high capacity, rapid water uptake and release sorbed water by compression-enabled switching from hydrophilic to hydrophobic state.
- **TA2 Goal:** Design, construct and optimize a system capable of meeting the DARPA SWaP and output requirements by leveraging the SMAF compressive release capability developed in TA1.



Density

Next-Gen Sorbent

TRL Analysis*



VG-2021-197-24

• Entering Phase I Program = TRL1/2

- Technology concept and/or application formulated.
- Limited analytic studies
 - Process in place to produce and evaluate SMAF materials
 - System concept created

• Exiting Base Program = TRL3/4

- Analytical and experimental critical function and/or characteristic proof of concept. Component and/or breadboard validation in laboratory environment
 - Material optimization performed
 - Breadboard system demonstration

Exiting Option Programs = TRL6

- Components and/or breadboard validation in relevant environment
 - Scalable sorbent production
 - Field demonstration in relevant environment (IV&V)

* Technology Readiness Levels in DoD, Defense Acquisition Guidebook 2010